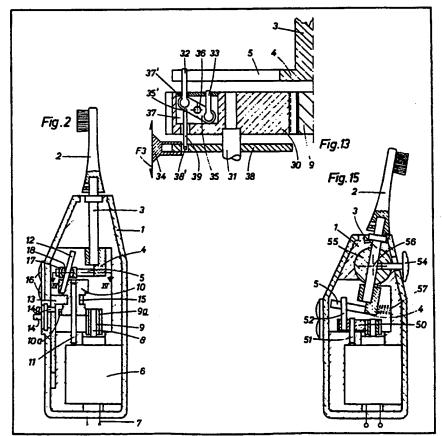
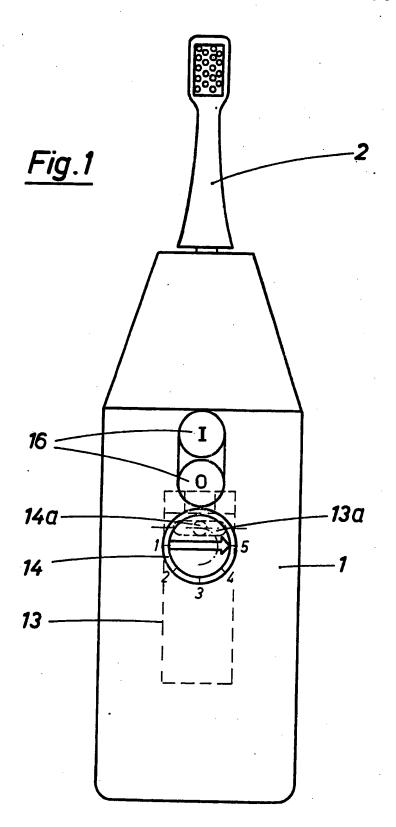
## (12) UK Patent Application (19) GB (11) 2 036 551

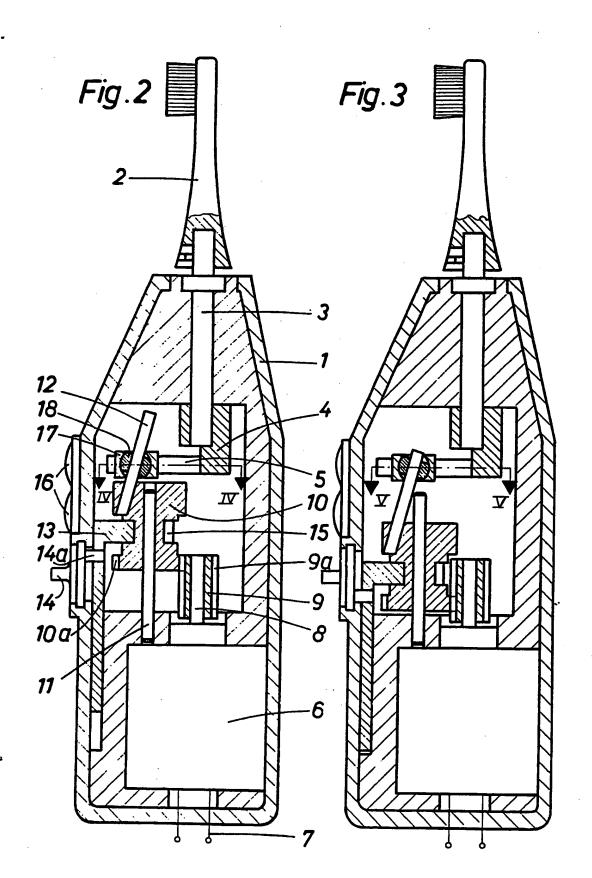
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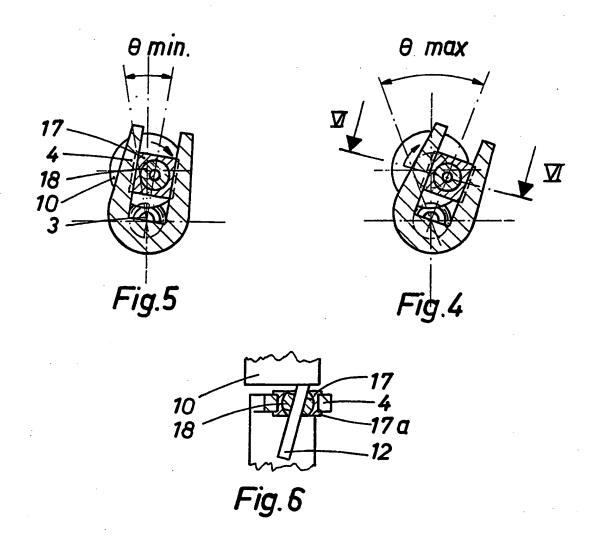
- Electrically driven hand-held toothbrush or massage apparatus
- (57) The apparatus operates with an eccentric pin (12), Fig. 2, which is driven via rotated support 10 by the motor (6) and engages in a freely displaceable manner in a longitudinal slot (5) of a fork (4) secured to instrument holder (3) to set the instrument holder in oscillatory motion about its longitudinal axis. To permit the oscillation amplitude to be adjusted without

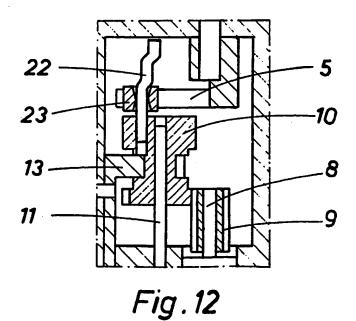
alteration of the oscillation frequency, the support (10) is axially displaceable on its axis of rotation (11) by means of an external operating knob (14), whereby the radius of rotation of the location of engagement in the longitudinal slot (5), of the eccentric pin (12) is variable. In Fig. 13, two pins 32, 33 are used which rotate about axis 31 and can alternatively engage in slot 5. In Fig. 15, the radius of rotation of the location of engagement of pin 52 in slot 5 is varied by tilting support 56 and hence attached fork 4.

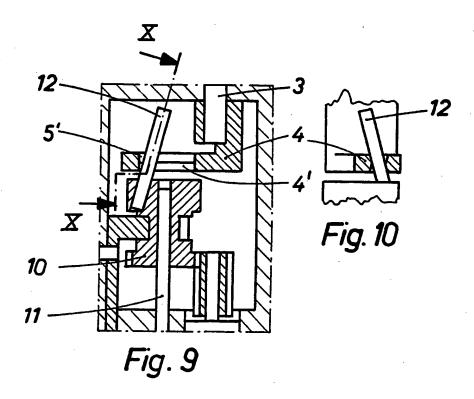


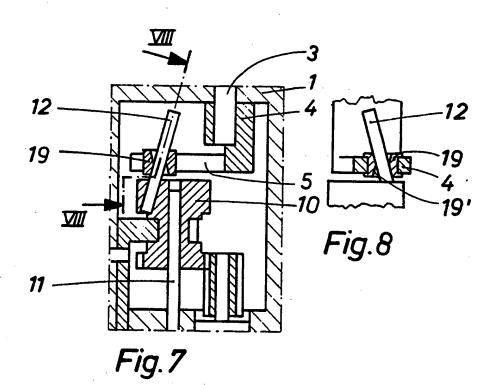


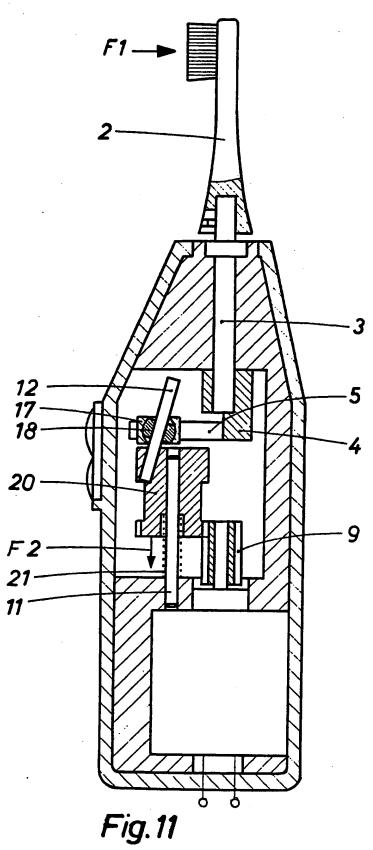


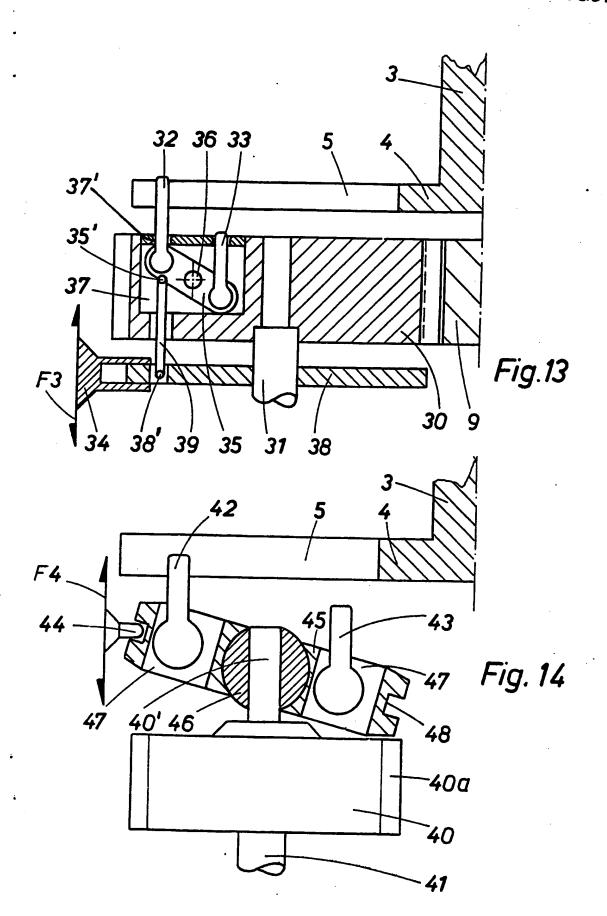


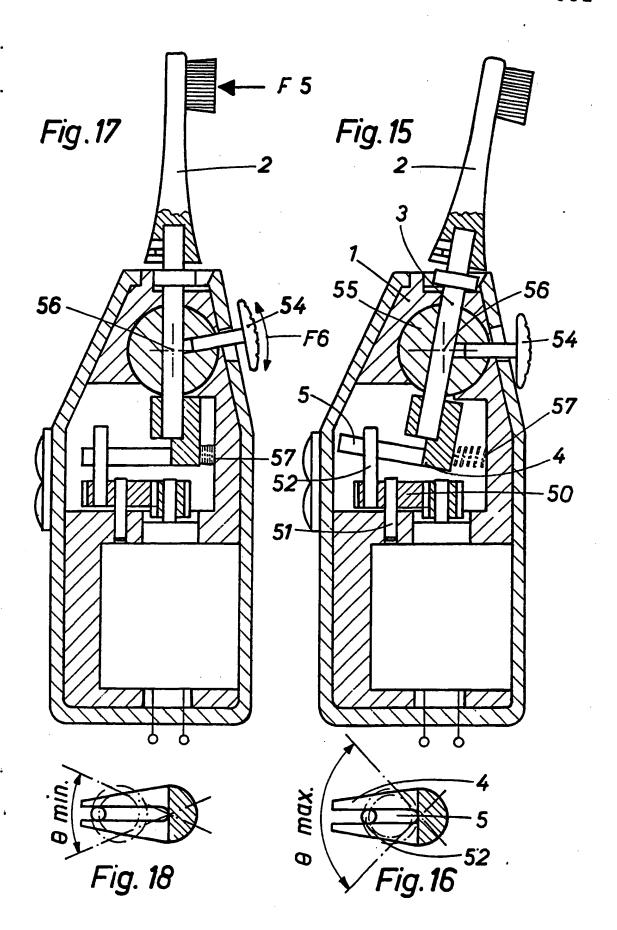












#### **SPECIFICATION**

Electrically driven hand-held apparatus for body care, in particular a toothbrush or massage apparatus

The invention relates to an electrically driven hand-held apparatus for body care of the kind indicated in the pre-characterising clause of claim 1, in 10 particular a toothbrush or a massage apparatus.

Known electrical toothbrushes of this kind have a direct current motor in the apparatus casing constructed in the form of a handgrip; the motor may be connected to the mains supply network or may be 15 fed from a battery, and its rotary motion is converted by means of a motion transformer to an oscillatory movement of the pushed-on toothbrush about its longitudinal axis. For this purpose a support in the form of a disc provided with an eccentric pin is 20 mounted on the motor shaft, and the inner end of the instrument holder has a radially extending fork attached thereto, the eccentric pin engaging between the arms thereof; the longitudinal axis of the instrument holder is radially offset relatively to the 25 axis of rotation about which the eccentric pin circulates, that is to say relatively to the motor axis or the axis of rotation of the disc, respectively, in such a manner that the rotating eccentric pin affords the instrument holder with the toothbrush pushed 30 thereon on oscillatory motion of constant oscillation amplitude about the shank of the toothbrush.

Such an oscillatory movement of the toothbrush is particularly effective for the care of teeth and mouth and permits above all an optimum massage of the 35 gums which is important for maintaining the health of the teeth and the gums; oscillation frequencies of the toothbrush of between approximately 40 and 60 Hz have been found most favourable for this purpose.

However, experience has shown that the sensitivity of the gums and the teeth to the brushing or the massage, respectively, differs widely from person to person, and in particular in the case of a gum disease, above all paradontosis, injuries and bleeding 45 may occur even by careful brushing with a normal brush. The pain threshold, also, is very different individually. In order to take account of these individual physiological conditions, the user of an electrical toothbrush heretofore had in general only the 50 possibility to use attachable toothbrushes with sufficiently soft bristles, and he had to take care that he did not press the brush down too hard. A reduction of the supply voltage of the motor would have the unfavourable consequence of a reduction of the rot-55 ary speed of the motor and thus a reduction of the oscillation frequency of the brush, thereby disadvantageously affecting the massage effect; moreover

the gums would be stressed as before in as much as it is squeezed to and fro through a path correspond-60 ing to the unchanged oscillation amplitude; when the gums are sensitive or diseased, this may lead to

tearing the tissue even at a relatively low massage

A reduction of the mechanical energy or output of 65 the oscillating treatment instrument without reduc-

tion of the oscillation frequency is frequently desirable even for general body massage apparatus, in order to be able to perform appropriately careful massages of sensitive or inflamed body regions or 70 for example for the purpose of make-up.

An electrical toothbrush of the kind described above is already known, in which a change of the distance between the longitudinal axis of the instrument holder and the axis of rotation of the 75 support for the eccentric pin is provided, so that thereby the oscillation amplitude can be adjusted within certain limits. This is attained by the fact that either the motor with the disc supporting the eccentric pin is mounted in the casing in a radially displaceable manner, or that the eccentric pin is located on a gearwheel which is mounted adjacent the motor shaft on a bearing plate and which meshes with a pinion secured on the motor shaft, and the entire bearing plate can be rotated about the motor 85 shaft. However, the first mentioned construction with a radially displaceable motor necessitates a complicated constructional design of the apparatus, in which case additionally the diameter of the apparatus casing must be correspondingly increased in an unfavourable manner; likewise the rotatable mounting of the entire bearing plate with the gearwheel carrying the eccentric pin in accordance with the other known constructional form and the necessary arrangement of the operating element for the adjustment of the bearing plate are very unfavourable in a constructional respect, and furthermore, upon displacement of the bearing plate in the peripheral direction of the casing, obviously also the rest position of the toothbrush, or the entire 100 angular range of the toothbrush oscillation is twisted relatively to the apparatus casing, respectively; this renders convenient manipulation of the apparatus difficult.

The invention is to provide a hand-held apparatus 105 of the kind referred to above in which the problem of changing the oscillation amplitude of the treatment instrument without influence upon its oscillation frequency is solved in a constructionally considerably simpler manner than heretofore and in which 110 the user can adjust the oscillation amplitude easily without reduction of the convenient manipulation.

This problem is solved according to the invention by means of the features stated in Patent Claim 1.

The main advantage of the hand-held apparatus 115 according to the invention resides in that for the purpose of changing the oscillation amplitude merely the degree of eccentricity of the eccentric pin must be variable in relation to the axis of rotation of its support, so that neither a radial displaceability of 120 the motor, nor a bearing plate rotatable about the motor shaft must be provided on which a gearwheel is mounted which carries the eccentric pin and is driven by the motor shaft. In a particularly advantageous and simple constructional form of the 125 hand-held apparatus according to the invention the eccentric pin is orientated on its support inclined to the axis of rotation thereof and this support is displaceably mounted in the direction of its axis of rotation, that is to say simply along its axis of rotation.

130 This permits a continuous change of the oscillation

amplitude by simple axial displacement of the support; this can be realised easily by means of a simple external operating element. In this case the support for the eccentric pin may be conveniently be a gearwheel which is mounted in a rotatable and axially displaceable manner on a stub parallel to the motor shaft and which meshes with a pinion fixed on the motor shaft.

A simple stepwise adjustment of the oscillation
amplitude is possible by means of the features indicated in patent claim 3. Advantageous constructions for a perfect guidance of the eccentric pin in the longitudinal slot are stated in patent claims 5 to 7. The construction according to patent claim 10 permits
the adjustment of two different oscillation amplitudes.

Another constructional solution for changing the oscillation amplitude is indicated in patent claims 8 and 9 and is based on a possibility to tilt the entire 20 instrument holder, so that the inner end thereof with the fork which embraces the eccentric pin is adjustable in relation to the axis of rotation of the eccentric pin support.

Finally even an automatic amplitude adjustment
25 may be provided as a function of the loading exerted
upon the treatment instrument, in accordance with
patent claim 12.

The invention is not limited only to hand-held apparatus with a rotating motor, but is also usable 30 for hand-held apparatus, in particular electrical toothbrushes with a swinging armature motor which, upon connection to the alternating current mains supply network oscillates directly at the supply network frequency; heretofore the instrument 35 holder of these hand-held apparatus is fixed directly to the swinging armature in the axial extension thereof. The construction in accordance with the invention permits now even hand-held apparatus with a swinging armature motor to be constructed in 40 such a manner that for the first time the oscillation amplitude is variable in a simple manner, in that the swinging armature drives the support with the eccentric pin in an oscillating manner and the instrument holder is mounted independently of the 45 swinging armature. Thus in this case a change of the oscillation amplitude of the instrument holder substantially does not influence the oscillation amplitude of the swinging armature itself, for which the swingin armature motor is dimensioned and

50 adjusted; this is extremely advantageous. If, in contrast, the feed voltage would be reduced, for example for the purpose of a more careful treatment, the motor torque would be reduced in an unfavourable manner.

55 The invention is explained in detail by means of constructional examples with reference to the drawings. There are shown in:

Fig. 1, a side view of a hand-held apparatus according to the invention in the form of an electrical 60 toothbrush,

Fig. 2, an axial section through the hand-held apparatus according to Fig. 1 with an adjustable eccentric pin which assumes its position corresponding to the greatest swing angle,

Fig. 3, the hand-held apparatus according to Fig. 2

in the eccentric position which corresponds to the smallest swing angle,

Fig. 4, a section on the line IV-IV in Fig. 2,

Fig. 5, a section on the line V-V in Fig. 3,

Fig. 6, a section on the line VI-VI in Fig. 4,

Fig. 7, a section through the parts essential for the invention, of a first varient of the example according to Figs. 1 to 6,

Fig. 8, a section on the line VIII-VIII in Fig. 7, after 75 rotation of the eccentric pin through 90°,

Fig. 9, a section through the parts essential for the invention, of a second variant of the example according to Figs. 1 to 6,

Fig. 10, a section on the line X-X in Fig. 9, after 80 rotation of the eccentric pin through 90°,

Fig. 11, the axial section through a second constructional form in which the oscillation amplitude is variable automatically as a function of the loading exerted upon the treatment instrument.

Fig. 12, the section through the parts essential for the invention of a third constructional form with the possibility of a stepwise adjustment of the oscillation amplitude,

Fig. 13, the diagrammatic illustration of the essen-90 tial parts of a fourth constructional form with a rocker member supporting two eccentric pins,

Fig. 14, a varient of the example according to Fig. 13,

Fig. 15, the axial section through a fifth construc-95 tional form with a tiltable instrument holder which assumes its position corresponding to the largest swing angle,

Fig. 16, a diagrammatic view from above upon the fork comprising the longitudinal slot and the eccentic pin according to Fig. 15,

Fig. 17, the constructional form according to Fig. 15 in the position of the instrument holder corresponding to the smallest swing angle, and

Fig. 18 a diagrammatic view from above upon the 105 fork comprising the longitudinal slot with the eccentric pin according to Fig. 17.

According to Figs. 1 to 3, the hand-held apparatus comprises a casing 1 with a push-on toothbrush 2 interchangeably attached to an instrument holder 3.

The instrument holder 3 in the form of a shaft is mounted in the casing 1 in a manner rotatable about its longitudinal axis, and at its inner end it carries a fork 4 with the longitudinal slot 5 between the two arms thereof which are orientated radially in relation to the longitudinal axis of the instrument holder 3 and the casing 1.

Furthermore, an electro-motor 6 which is illustrated merely diagrammatically, is accommodated in the casing 1 and involves preferably a direct current motor; it is connectable to the current supply by means of the terminals 7; in the case of an alternating current mains supply network, obviously a rectifier is additionally provided. A hand-held apparatus fed from a battery or an accumulator may also be involved.

A pinion 9 is non-rotatably mounted on the motor shaft 8 and has peripheral teeth 9a which mesh with the peripheral teeth 10a of a rotation-symmetrical substantially cylindrical support 10. This support 10 is mounted rotatably and freely displaceably in an

axial direction on a stub 11 which is parallel to the motor shaft 8; it supports an eccentric pin 12 on its side facing the fork 4. The longitudinal axis of this eccentric pin 12 is orientated inclined to the axis of 5 rotation of the support 10, that is to say also to the stub 11 and is so dimensioned and arranged that it does not intersect the extension of the stub 11. The eccentric pin 12 extends in a freely displaceable manner through the diametrical bore of a ball 18 of a 10 ball joint which forms a guide member 17 which is freely displaceable within the longitudinal slot 5 of the fork 4. As indicated in Figs. 4 and 6, the two sides facing the fork arms, of the joint bearing of the guide member 17 comprise flanges 17a which engage on 15 both sides over these fork arms, so that the guide member 17 is retained in the longitudinal slot displaceable along the fork 4.

The middle region of the support 10 is provided with a ring groove 15 (Fig. 2) into which engages the 20 radially orientated limb of an L-shaped slider member 13 the other limb of which is axially displaceably mounted at the inside of the outer wall of the casing 1 and comprises a transverse slot 13a (Fig. 1). The slider member 13, and thus also the 25 support 10 with the eccentric pin 12 can be displaced axially in relation to the axis of rotation thereof by means of an external operating element 14 in the form of a rotary knob (Fig. 1) to the inside of which a stub 14a is attached which engages into the trans-30 verse slot 13a of the slider member 13, so that because of the inclined position of the eccentric pin 12 the location of engagement thereof in the longitudinal slot 5 and thereby the effective eccentricity is changed.

Two water-tight push-buttons 16 for switching the electro-motor 6 on and off are provided above the operating element.

When the motor is running, the support 10 and thus also the eccentric pin 12 is set in a rotary motion 40 about the stub 11, so that the fork 4 driven by the eccentric pin 12 and thereby the instrument holder 3 carrying the push-on toothbrush in a non-rotatable manner perform an oscillating movement about its longitudinal axis. For this purpose the arrangement is obviously made so that the circle described by the engagement point of the eccentric pin 12 in the longitudinal slot 5 lies outside the longitudinal axis, or the swing axis, respectively, of the intrument holder 3. The rotary speed of the motor and the reduction gear ratio of the drive have been selected such that the oscillation frequency amounts to at least approximately 50 Hz.

The swing angle, or the oscillation amplitude, respectively, of the instrument holder 3 and thus 55 also that of the toothbrush 2 is the smaller, the smaller is the radial spacing between the axis of rotation 11 of the eccentric pin 12 and the location of engagement thereof in the longitudinal slot 5. Since because of the inclination under consideration of the 60 eccentric pin 12 in accordance with Figs. 2 and 3 this radial spacing is greatest in the forwardly displaced position of the support 10 in which it is disposed closest to the longitudinal slot 5, this position illustrated in Fig. 2 of the eccentric pin 12 corresponds to the greatest swing angle Θ<sub>max</sub> (Fig. 4) which is fixed

preferably to a value between 40° and 60°, for example 50°. The other end position of the support 10 illustrated in Fig. 3 in which it assumes its position furthest away from the longitudinal slot 5, corres-70 ponds to the minimum swing angle Θ<sub>min</sub> (Fig. 5) which advantageously amounts to only from 10° to 20°, for example 15°. According to Fig. 1 five different positions of the eccentric and thus also oscillation amplitudes and swing angles, respectively, are 75 marked on the periphery of the operating element 14, in order to facilitate the adjustment which may be performed continuously.

In the varient according to Figs. 7 and 8, the guide member 19 which is displaceable in the longitudinal so slot 5 of the fork 4 and which is penetrated by the eccentric pin 12, consists of a bush with a double-conical inner peripheral wall 19' which widens out to both ends of the bush and the cone angle of which is adjusted to the inclined orientation of the eccentric pin 12, so that the latter may slide satisfactorily in the bush 19.

In the variant illustrated in Figs. 9 and 10, no guide member is provided for the eccentric pin 12 which engages directly in the longitudinal slot 5 closed in 1 this case, of a member 4 fixed to the instrument holder 3. The walls 4' limiting the longitudinal slot 5' are profiled in a double-conical manner corresponding to the inclination of the eccentric pin 12 lying against them.

The remaining construction of the examples illustrated in Figs. 7 and 8, and Figs. 9 and 10, respectively, corresponds to the constructional example according to Figs. 1 to 6.

The constructional example according to Fig. 11 100 does not comprise an external operating element for adjusting the support 20 with the eccentric pin 12, but is provided with a return spring 21 which surrounds the stub 11 and which normally retains the support 20 in its forward position illustrated in Fig. 105 11, which corresponds to the largest oscillation amplitude of the toothbrush 2, as explained with reference to the first constructional example. As in this constructional example according to Figs. 1 to 6, the eccentric pin 12 extends through the ball 18 of a 110 guide member 17 which is constructed in the form of a ball joint and which is displaceable in the longitudinal slot 5 of the fork 4 attached to the instrument holder 3. When during the use of the hand-held apparatus a force is exerted on the bristles of the 115 toothbrush 2 in the direction of the arrow F1, a reaction force is exerted by the limiting wall of the longitudinal slot 5 or the diametrical bore of the ball 18, respectively, upon the eccentric pin 12, which force has an axial component because of the inclined position of the said pin. This has as a consequence an automatic axial displacement of the support 20 in the sense of the arrow F2 against the effect of the return spring 21, this displacement being the greater the more the toothbrush 2 is being 125 loaded, i.e. the more the user presses the toothbrush

against the teeth or the gums. It is attained in this way that the oscillation amplitude of the toothbrush decreases automatically with increasing loading and consequently the risk of injury is reduced. Upon 130 relieving the toothbrush of the load, the eccentric pin

10 thereof is fixed thereby, in order that this position does not change under the effect of the spring 21. When the user desires an automatic adjustment of the oscillation amplitude to the pressing force exerted by the brush, it is merely necessary for him 15 to release the retaining or locking device, whereupon the spring 21 becomes effective again.

In the constructional example according to Fig. 12, the eccentric pin 22 comprises sections which are radially offset in stepwise manner in relation to its 20 longitudinal axis or its axis of rotation, respectively, and extends through a bush which serves as a guide member 23 in the longitudinal slot 5 and which has a convexly inwardly curved inner peripheral wall. The remaining construction of this constructional exam-25 ple corresponds to the example according to Figs. 1 to 6. Thus the eccentric pin 22 is again located on a support 10 which is driven by the motor shaft 8 and which is axially displaceable from the outside on its stub 11 by means of a slider member 13; in the 30 example under consideration this adjustment occurs in a stepwise manner. The magnitude of the effective eccentricity and thus the oscillation amplitude depends in this case upon the fact which one of the radially offset regions of the eccentric pin 22 is 35 located within the longitudinal slot 5 or the guide member 23, respectively, the convexly curved inner wall of which permits the easy displacement of the deformed eccentric pin 22.

In the constructional example according to Fig. 13, 40 two eccentric pins 32 and 33 are attached to the ends of a rocker member 35 which is mounted in a recess 37 of the support 30 and is rotatable about the tipping axis 36 which is orientated perpendicular to the axis of rotation of the said support. The support 30 45 has peripheral teeth 30a which mesh with the pinion 9 on the motor shaft, and when the motor runs it is set in rotary motion about the stub 31. The rocker member 35 is disposed radially and eccentrically in relation to the stub 31, so that the two eccentric pins 50 32 and 33 have different spacings from their common axis of rotation formed by the stub 31. In the position illustrated in Fig. 13, of the rocker member 35 the eccentric pin 32 located at a larger distance from the stub 31 engages in the longitudinal slot 5 of 55 the fork 4 at the instrument holder 3 and thereby defines the larger oscillation amplitude of the treatment instrument; in the other position of the rocker member 35 in which the latter is rotated about the tipping axis 36 in a clockwise direction in accordance 60 with Fig. 13, the eccentric pin 33 engages in the longitudinal slot 5, so that then the instrument holder 3 swings with the smaller oscillation amplitude. In order that the two eccentric pins 32 and 33 maintain always at least approximately their position parallel 65 to the stub 31, they project with sufficient play

through openings 37' which are provided in a plate which covers the recess 37. For the purpose of displacing the rocker member 35 there serve a disc 38 which rotates together with the support 30 and is 70 arranged underneath it in an axially displaceable manner, and a small rod 39 which extends with sufficient play through an opening in the bottom of the recess 37; the one end of the rod 39 is pivotally attached to the rocker member 35 at 35', its other 75 end being pivotally attached to the disc 38 at 38'. An external operating element 34 the inner fork-shaped end of which engages around the edge of the disc 38, can be displaced in the sense of the double-arrow F3 and thereby drives the disc 38 which is non-80 rotatably and axially displaceably arranged on a sleeve 30' which is secured on the support 30 and which is rotatably mounted on the stub 31.

The constructional example according to Fig. 14 again comprises a support 40 which is rotatably 85 mounted on the stub 41 and at which a rocker member 45 is rotatably mounted on a cylindrical stub 46 and has two eccentric pins 42 and 43 attached in recesses 47, the stub 46 being securely seated on a short tube member 40' which projects 90 from the support 40 in the extension of the stub 41. The two eccentric pins 42 and 43 have different spacings from the axis of rotation of the support 40 which for the purpose of drive, again has peripheral teeth 40a which mesh with the pinion on the motor shaft. 95 An operating element 44 which is axially displaceable in the sense of the double-arrow F4 has an inner protrusion which engages in a ring groove 48 on the periphery of the rocker member 45 which in this way is rotatable to its one or its other operative position. 100 In the rocker member position illustrated in Fig. 14 the eccentric pin 42 which has the larger spacing from its axis of rotation engages in the longitudinal slot 5 of the fork 4 at the instrument holder 3 and thereby defines the larger oscillation amplitude, whereas in the other rocker member position with engagement of the eccentric pin 43 in the longitudinal slot 5, the instrument holder swings with a smaller amplitude. Means not illustrated ensure that the two eccentric pins 42 and 43 retain always their axial 110 alignment to a substantial extent; for this purpose, for example, a disc with guide openings may be provided which rotates above the rocker member 45 together with the support 45 and through which the eccentric pins extend with sufficient play.

115 Furthermore, in both examples according to Figs. 13 and 14 the arrangement is made so that the two eccentric pins can never engage simultaneously in the longitudinal slot 5, or the rocker member cannot come to standstill in a position in which both eccen-120 tric pins engage in the longitudinal slot, respectively. Moreover a return spring not illustrated is provided which when the motor is switched off moves the instrument holder with the fork 4 with displacement of the rocker member, to a middle rest position in which the rocker member can be switched over without difficulty.

The constructional form illustrated in Figs. 15 to 18 comprises an instrument holder 3 which is mounted rotatable about its longitudinal axis, in a diametrical 130 bore of a pivot pin 55 and which furthermore is

mounted tiltable about a tipping axis 56 by means of these pivot pins 55 within the casing 1, the tipping axis 56 being orientated perpendicular to the longitudinal axis of the instrument holder 3 as well as also the fork 4 fixed to its inner end and having the longitudinal slot 5. The eccentric pin 52 engaging in the longitudinal slot 5 again is seated on a support 50 which is set in rotary motion about the stub 51 by the motor shaft and extends parallel to its axis of 10 rotation. By means of an external operating element 54 which is secured to the pivot pin 55, the instrument holder 3 with the push-on toothbrush 2 attached thereto may be swung through a certain angle in the sense of the double-arrow F6 between 15 the first position illustrated in Fig. 15 and the second position illustrated in Fig. 17. In the first position in which in the example under consideration the instrument holder 3 is inclined relatively to the longitudinal axis of the casing, the radial distance of the 20 eccentric pin 52 from the longitudinal axis, or the swing axis, respectively, of the instrument holder 3 is smallest and therefore the swing angle  $\Theta_{max}$  (Fig. 16) is greatest. In the second position (Fig. 17) the radial spacing referred to is greatest and therefore 25 the swing angle  $\Theta_{min}$  (Fig. 18) is smallest. Under certain circumstances the instrument holder 3 may be fixed in every position selected, by means of a retaining device not illustrated.

In a modified constructional form the instrument 30 holder 3 is held normally, with the treatment instrument not loaded, in a position corresponding to the largest swing angle (Fig. 15) by means of a return spring 57 illustrated by a broken line. The treatment instrument, or the push-on toothbrush, respectively, 35 may then by pushed on in such a way that the pressing force exerted during the treatment in the sense of the arrow F5 according to Fig. 17 rotates the instrument holder in the direction of the position corresponding to the smallest swing angle, against 40 the effect of the return spring 57. In this case in which an external operating element 54 may be omitted, the reduction of the oscillation amplitude occurs therefore automatically, as in the constructional example according to Fig. 11, as a function of 45 the pressing force exerted by the user.

The invention is not limited to the constructional examples illustrated, but permits manifold variants in respect of the construction of the invidiual parts. Furthermore, the features according to the invention, in particular the embodiments according to Figs. 1 to 12, are applicable without difficulties to hand-held apparatus with a swing armature motor, in order that in these apparatus, too, the oscillation amplitude of the instrument holder separated from 55 the swing armature may be varied in a simple manner.

#### **CLAIMS**

An electrically driven hand-held apparatus for body care such as a toothbrush or massage
 apparatus, comprising an instrument holder which is adapted for the attachment of a treatment instrument and which is drivable for oscillation about its longitudinal axis, a motor, a rotatably mounted support driven by the motor, an eccentric pin which is secured to the support, and an inner part of the

- instrument holder defining a longitudinal slot which slot extends substantially radially in respect of the longitudinal axis of the instrument holder and in which the eccentric pin engages in a freely displace-70 able manner, the radial distance between the axis of rotation of the support of the eccentric pin and the location of engagement thereof in the longitudinal slot being variable.
- An apparatus according to claim 1, in which
   the eccentric pin is orientated on its support and inclined to the axis of rotation of the latter, the support being mounted for displacement in the direction of its axis or rotation.
- An apparatus according to claim 1, in which the eccentric pin comprises sections which are radially offset in a stepwise manner in respect of its longitudinal axis and its support is displaceable in a stepwise manner in the direction of its axis of rotation.
- 85 4. An apparatus according to claim 2 or 3, in which the support for the eccentric pin is rotatably and axially displaceably mounted on a stub which is parallel to a shaft of the motor and comprises peripheral teeth which mesh with the teeth of a pin-90 ion which is fastened on the motor shaft.
- An apparatus according to any one of claims 1
  to 4, in which a guide member for the eccentric pin is
  freely displaceably mounted within the longitudinal
  slot and comprises a ball joint with a ball which pos95 sesses a diametrical bore penetrated by the eccentric
  pin.
- An apparatus according to any one of claims 1
  to 4, in which a guide member for the eccentric pin is
  freely displaceably mounted within the longitudinal
   slot and comprises a bush with a double-conical
  inner peripheral wall which widens towards both
  ends of the bush and the cone angle of which is
  adjusted to the inclined orientation of the eccentric
  pin.
- 105
  7. An apparatus according to any one of claims 1 to 4, in which the walls of the holder defining the longitudinal slot are profiled in a double-conical manner corresponding to the inclination of the eccentric pin engaging them.
- 8. An apparatus according to claim 3, in which a guide member for the eccentric pin is mounted within the longitudinal slot in a freely displaceable manner, the said guide member being in the form of a bush having a convexly inwardly curved inner peripheral wall.
- An electrically driven hand-held apparatus for body care, such as a toothbrush or massage apparatus, comprising an instrument holder which is adapted for the push-on attachment of a treatment instrument and which is drivable to oscillate about its longitudinal axis, a motor, a rotatably mounted support driven by the motor, an eccentric pin which is secured to the support, and an inner member of the instrument holder defining a longitudinal slot which slot extends substantially radially in respect of the longitudinal axis of the instrument holder and in which the eccentric pin engages in a freely displaceable manner, the instrument holder being mounted for tipping movement about an axis which is orien-

130 tated perpendicular to its longitudinal axis as well as

also substantially perpendicular to the longitudinal direction of the longitudinal slot, so that when the instrument holder is tipped the radial spacing between the longitudinal axis thereof and the axis of rotation of the support for the eccentric pin is variable

- An apparatus according to claim 9, in which a substantially cylindrical section of the instrument holder is mounted in a diametrical bore of a cylindrical pivot stub which in turn is rotatable about its axis of rotation which forms the tipping axis for the instrument holder.
- An apparatus according to claim 1, in which two eccentric pins are arranged at the ends of a
   rocker member at a different spacing from the axis of rotation of their common support, the rocker member being tiltable about an axis which is perpendicular to the axis of rotation of the support, between a first position and a second position,
   respectively, in which respectively one of the eccen-
- tric pins engages in the longitudinal slot.

  12. An apparatus according to any one of claims
  1 to 11, in which the position of the support for the
  eccentric pin or the position of the instrument hol25 der, respectively, is adjustable by means of an
  operating member.
- An apparatus according to claim 1, in which the support for the eccentric pin or the instrument holder is subjected to the effect of a return spring
   which when the treatment instrument is not loaded retains the support or the instrument holder, respectively, in a position which corresponds to the largest oscillation amplitude, and is adjustable in the direction of the position corresponding to the smallest
   oscillation amplitude by the loading exerted on the treatment instrument against the effect of the return spring.
- 14. An electrically driven head-held apparatus for body care, such as toothbrush or massage 40 apparatus, substantially as hereinbefore described with reference to Figs. 1 to 10, or Fig. 11, or Fig. 12, or Figs. 13 and 14, or Figs. 15 to 18 of the accompanying drawings.

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